



vowel [ɛ], with blending strengths slightly favoring target of wide vowel

# Learnability of Derivationally Opaque Processes in the Gestural Harmony Model Caitlin Smith<sup>1</sup> & Charlie O'Hara<sup>2</sup>

Undergoer

**∧**Raised

\_owered

 With correct gestural strength settings, Gestural Harmony Model can generate both stepwise and saltatory height harmonies

Are stepwise and saltatory height harmonies equally learnable?

- Task: set constriction degree targets and blending strengths for vowel and dorsal consonant gestures such that learner reproduces teacher's vowel raising pattern
- Patterns tested: Four-height stepwise raising before high vowel trigger (Nzebi-like)
  - Four-height saltatory raising before high vowel trigger (unattested)
- Ran 100 models of each type until convergence Learning Algorithm
- Initialize target constriction degree of 16 mm (i.e., all vowels start as [a]) and random strength (between 1 and 20)
- 2. On each iteration randomly generate (V)CV sequence
- 3. If  $V_2$  is a trigger of harmony, it overlaps  $V_1$ , resulting in blending
- 4. If C is dorsal /g/, following V overlaps it, resulting in blending
- 5. If learner produces error (segment with target farther than 0.2 mm from teacher's production):
- a. Update constriction degree target of learner's tongue body gesture to produce a constriction degree that better matches teacher's output
- b. In cases of blending: update strength of learner's tongue body gesture to produce a constriction degree that better matches teacher's output

In the Gestural Harmony Model, the stepwise vowel raising pattern is faster/easier to learn than the saltatory vowel raising pattern

- Assuming standard feature theory and markedness/faithfulness constraints, neither chain shifts nor saltation are derivable in Harmonic Grammar (Albright, Magri, & Michaels 2008; Farris-Trimble 2008; White 2013)
- Assuming non-standard features and/or constraint definitions, both opaque patterns are derivable in Harmonic Grammar
- Necessary conditions for each type of pattern (Magri 2018):
- Chain shifts: There exists a constraint **C** such that  $v(\epsilon) \rightarrow [i] > v(\epsilon) \rightarrow [e] + v(e) \rightarrow [i])^*$
- Saltation: There exists a constraint **S** such that  $v(\epsilon) \rightarrow [i] < v(\epsilon) \rightarrow [e] + v(e) \rightarrow [i])^*$
- \*where  $v(x \rightarrow y)$  indicates the number of violations of mapping  $x \rightarrow y$

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## The Gestural Gradual Learning Algorithm



![](_page_0_Picture_46.jpeg)

	Stepwise	Saltation
Scalar Faithfulness	0%	34%
Distinct Faithfulness	28%	100%
and saltation height ha	armonies pre	edict